

Traffic Control in Industrial Automation Networks

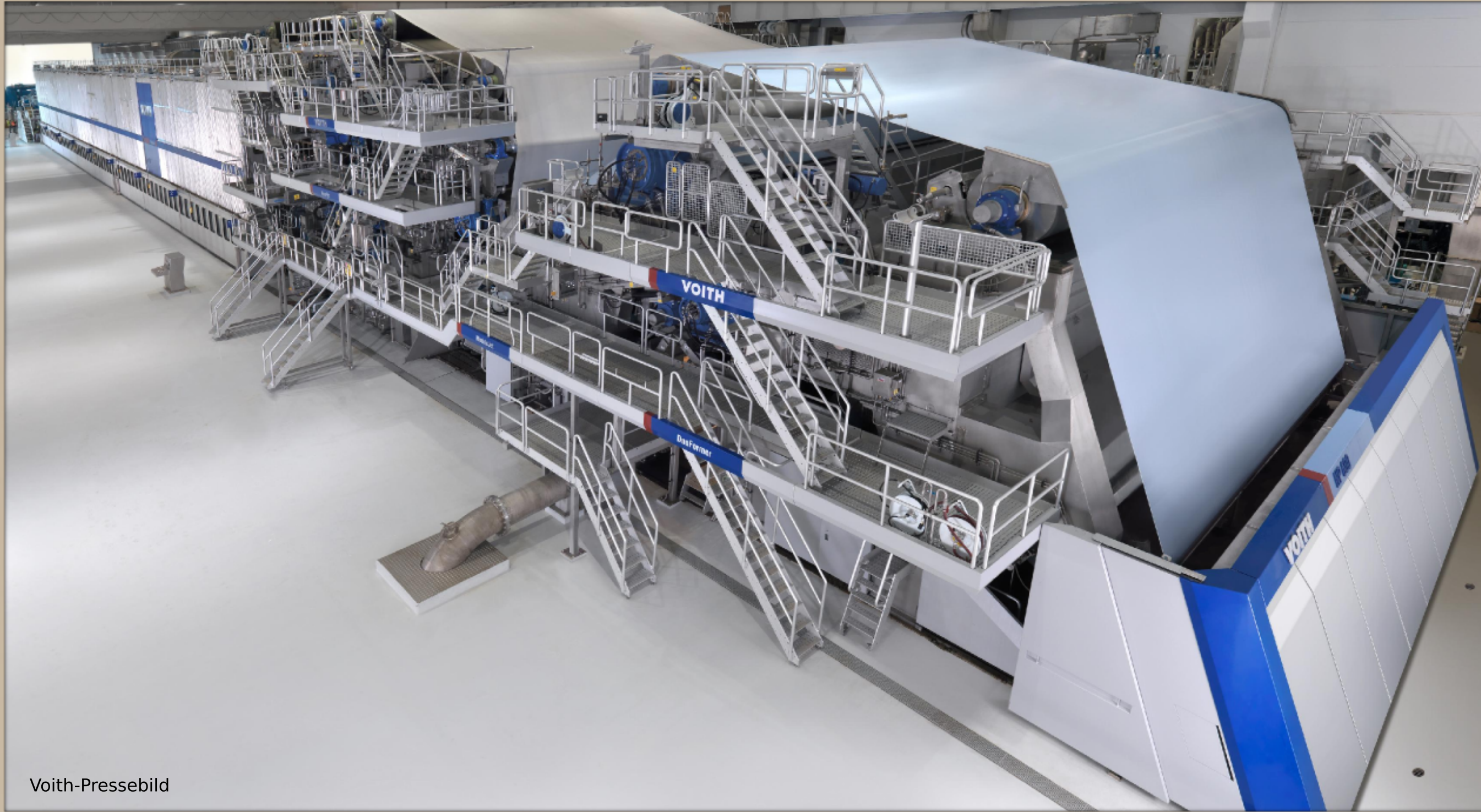
with focus on Paper Machines

Masterstudium:
Technische Informatik

Christian Mauser

Technische Universität Wien
Institut für Rechnergestützte Automation
Arbeitsbereich: Automatisierungssysteme
Betreuer: Ao.Univ.-Prof. Dr. Wolfgang Kastner
Univ.-Ass. Dipl.Ing. Lukas Kramer

Problem Environment



Industrial Automation Networks

A trend towards **Ethernet-based** automation networks can be observed!

- ➔ more and more subsystems share the **same network medium**
- ➔ the probability of **unwanted influences** between subsystems rises
- ➔ an **Internet connection** is often available
- ➔ the network is vulnerable to threats like **intrusion, malware, etc.**

Aim of the Thesis

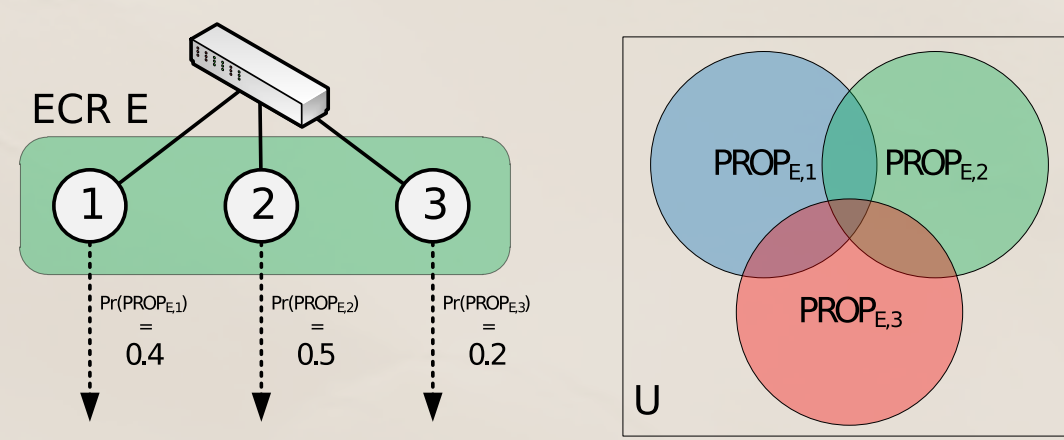
Improvement of **Dependability** and **Security** of industrial automation networks!

Error

Unintended state of the automation network, caused by one or more faulty hosts that pollute the network with **unwanted traffic** (e.g. flooding attack).

Error Propagation Probability (EPP)

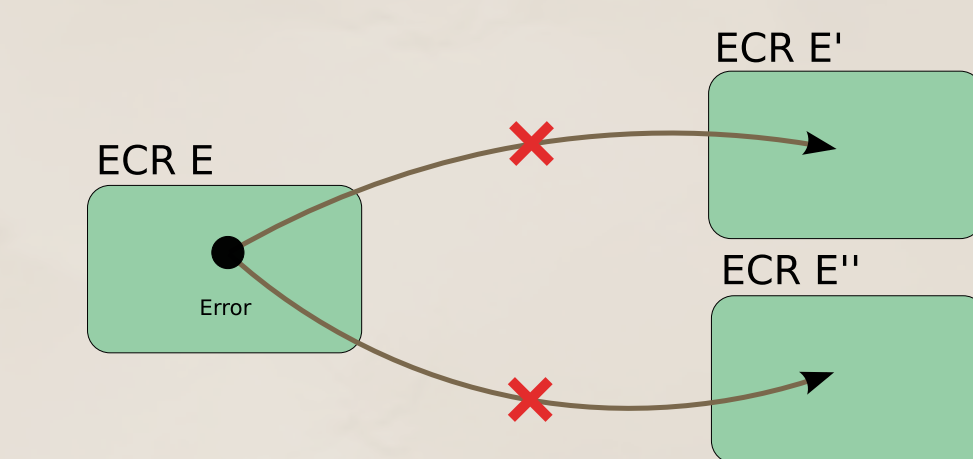
Probability, that an error is propagated from the automation network to its environment (e.g., paper machine).



Lower EPP means higher level of dependability/security!

Error Containment Coverage (ECC)

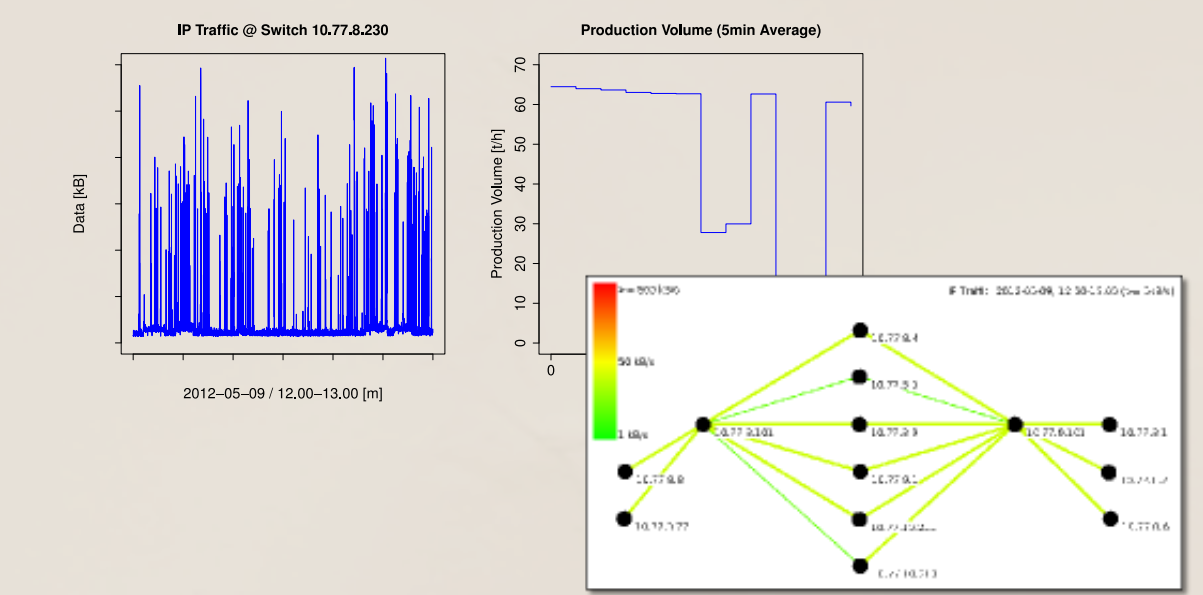
Probability, that an error is detected within an **Error Containment Region (ECR)**.



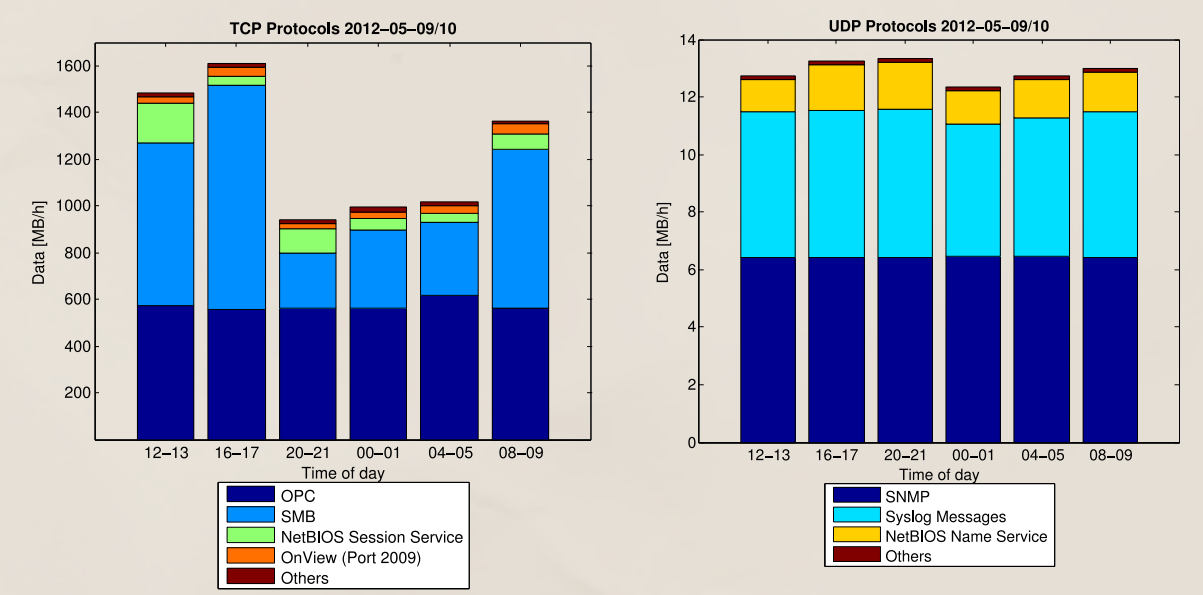
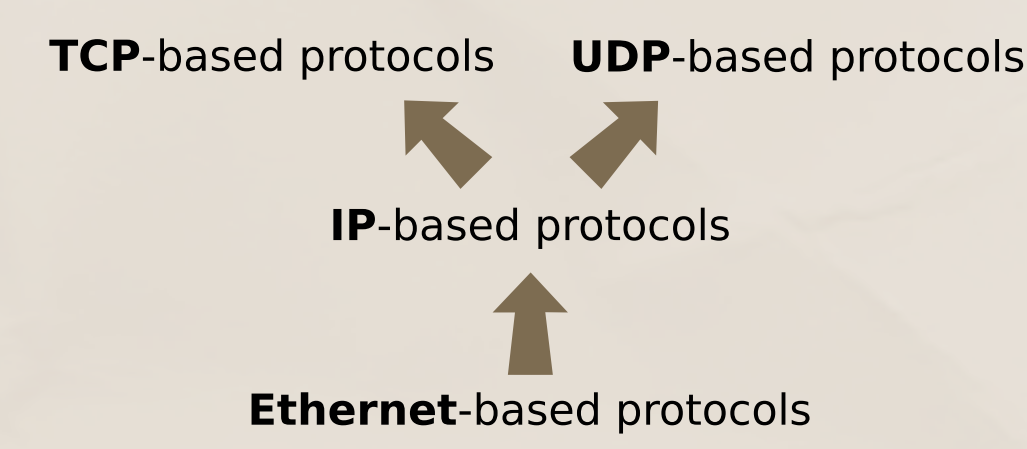
Higher ECC means higher level of dependability/security!

Quantitative Traffic Analysis

- ➔ **Traffic Graphs** visualizing cumulated traffic per second
- ➔ **Traffic Maps** visualizing point-to-point links



Semantic Traffic Analysis



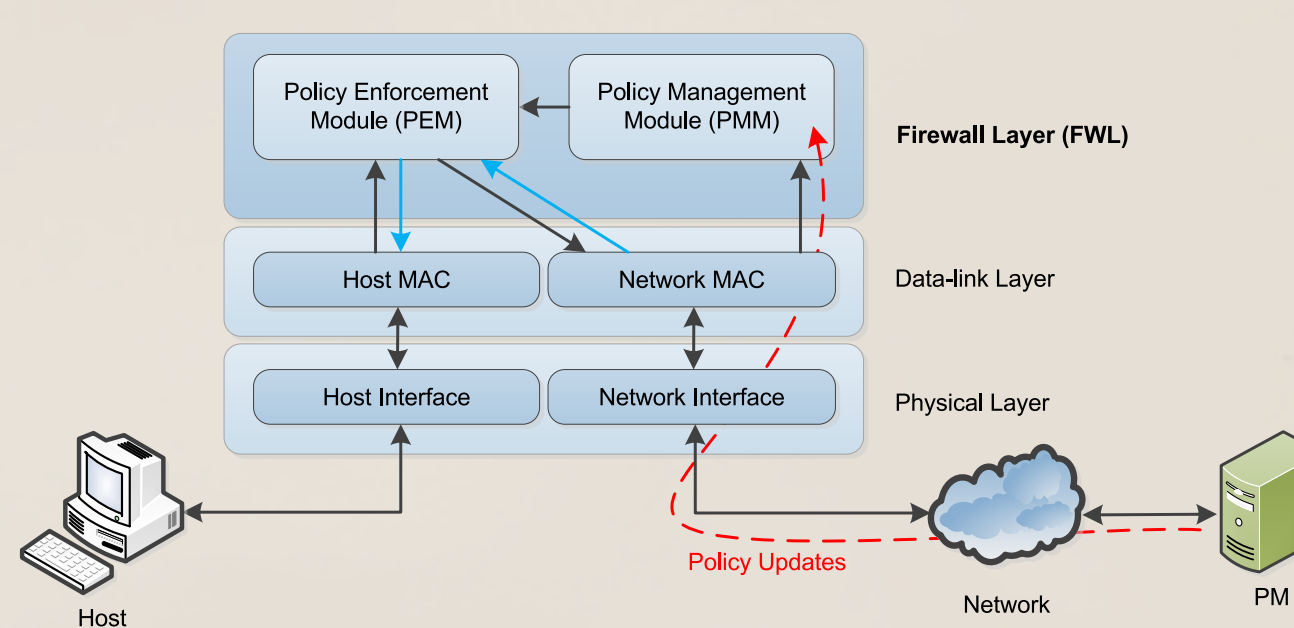
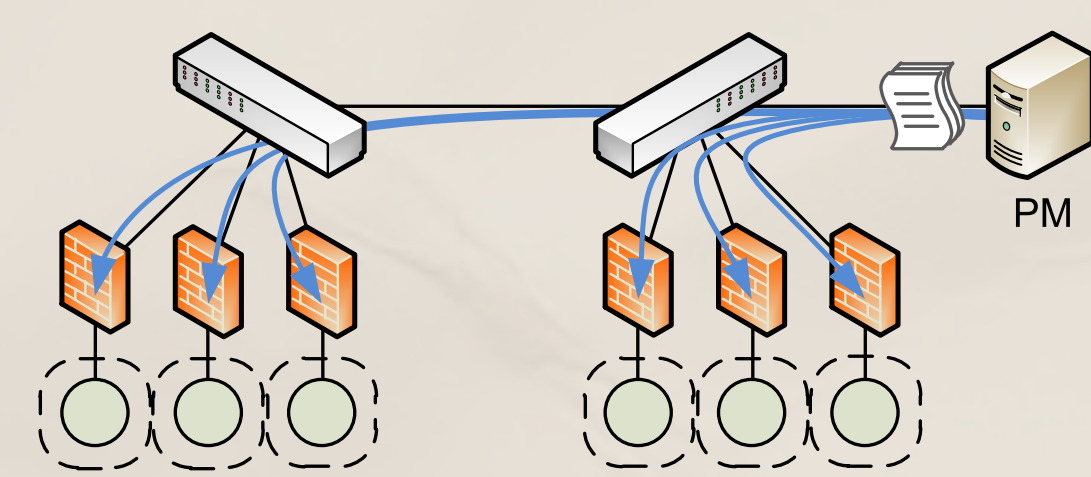
Theory

Analysis

Approaches

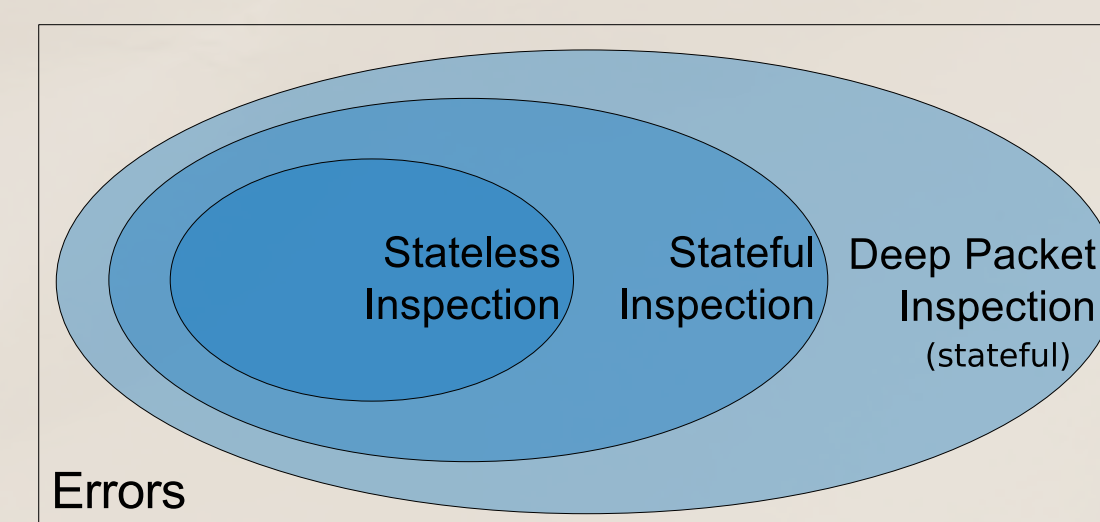
Distributed Firewall

- ➔ **Distributed policy enforcement** by Local Firewalls (LFWs)
- ➔ **Central policy definition** by Policy Manager (PM)



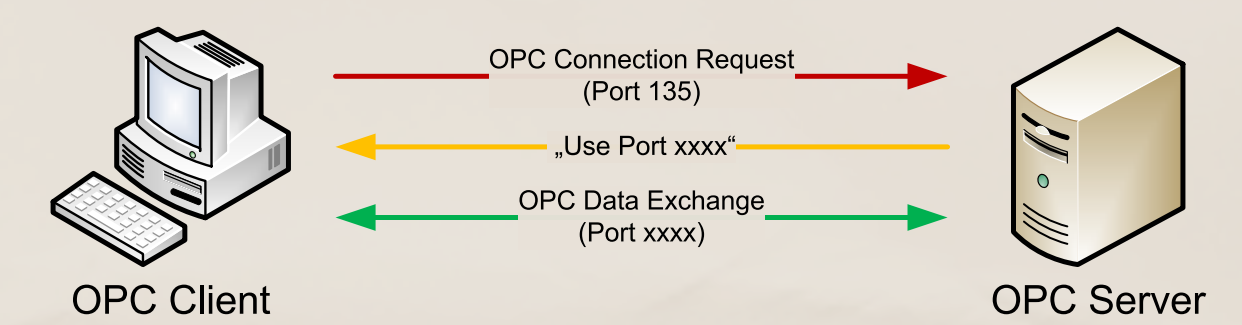
- ➔ Minimal size of Error Containment Regions (ECRs)
- ➔ **Improved Error Propagation Probability (EPP)!**

Smart Packet Filtering



- ➔ **Deep Packet Inspection** detects more error events than common filtering techniques
- ➔ **Improved Error Containment Coverage (ECC)!**

- ➔ Higher computational effort than common techniques
- ➔ Application-specific knowledge necessary
- ➔ Reasonable if port-based filtering is not possible, e.g. OPC



Formal Proofs

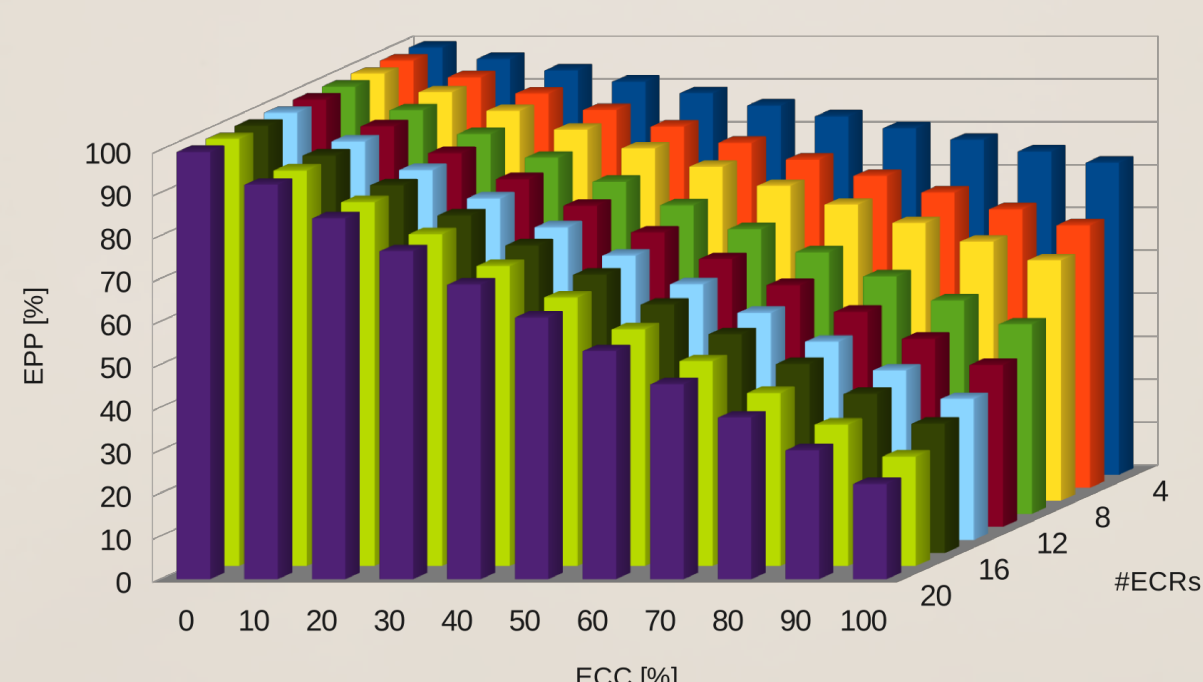
Theorem 1. Let $A = \{e_1, \dots, e_m\}$ be an automation network with m ECRs and $A' = \{e_1, \dots, e_m, e_{m+1}\}$ be an automation network with $m+1$ ECRs, which is derived from A by splitting an arbitrary ECR (w.l.o.g. let's say e_m) into two non-empty smaller ECRs e_{m+1} and e_m' . Then

$$EPP(A) \geq EPP(A')$$

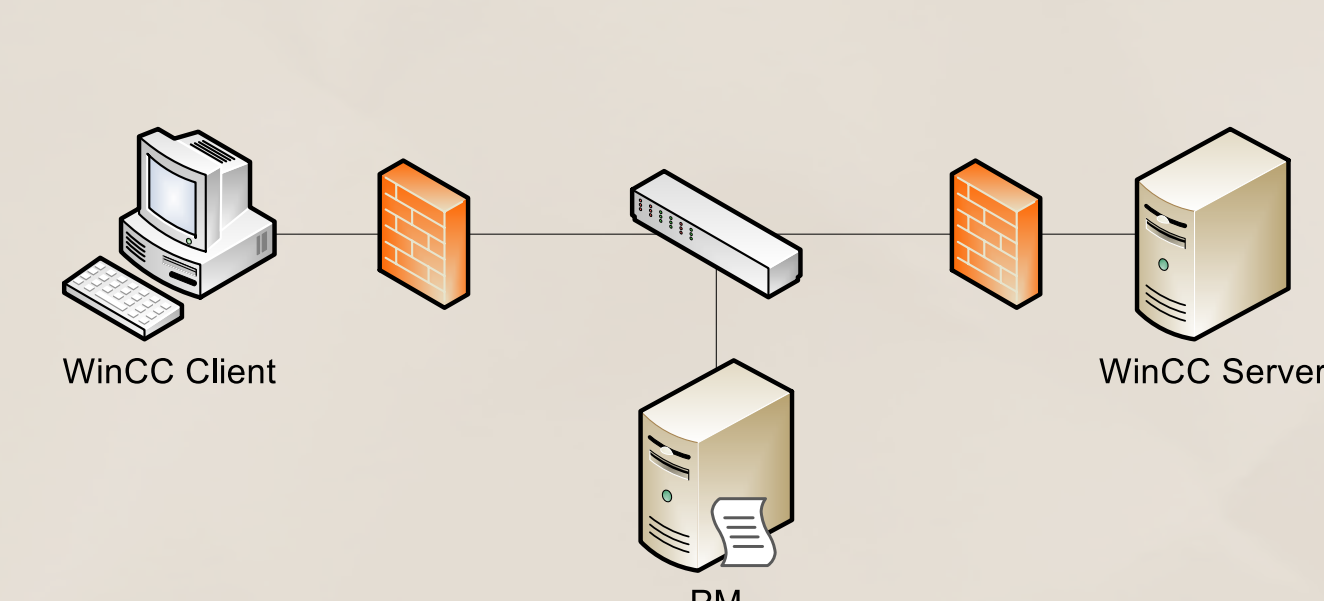
Theorem 2. Let A_d be an automation network using packet filters with stateless inspection. Furthermore, let A_{df} be the same automation network, but with stateful inspection firewalls and A_{dp} the same network with deep packet inspection firewalls. Moreover, let E be an arbitrary ECR, contained in the corresponding networks. Then the following property holds:

$$ECC(E, A_d) < ECC(E, A_{df}) < ECC(E, A_{dp})$$

Simulation



Prototypical Implementation



Evaluation Results

- ➔ **Formal Proofs, Simulation**
- ➔ **Distributed Firewall** minimizes the number of ECRs, and therefore **decreases EPP**
- ➔ **Deep Packet Inspection** improves ECC and thus **decreases EPP** also
- ➔ **Prototypical Implementation**
- ➔ Combination of Distributed Firewall and Deep Packet Inspection is **realizable**

Evaluation